

Integral transforms of fractional derivatives

(continued...)

Mellin transform — basic facts

Mellin transform of integer order derivatives

Integrating repeatedly by parts:

$$\begin{aligned} \mathcal{M}\{f^{(n)}(t); s\} &= \int_0^\infty f^{(n)}(t) t^{s-1} dt \\ &= [f^{(n-1)}(t) t^{s-1}]_0^\infty - (s-1) \int_0^\infty f^{(n-1)}(t) t^{s-2} dt \\ &= [f^{(n-1)}(t) t^{s-1}]_0^\infty - (s-1) \mathcal{M}\{f^{(n-1)}(t); s-1\} \\ &= \dots \\ &= \sum_{k=0}^{n-1} (-1)^k \frac{\Gamma(s)}{\Gamma(s-k)} [f^{(n-k-1)}(t) t^{s-k-1}]_0^\infty \\ &\quad + (-1)^n \frac{\Gamma(s)}{\Gamma(s-n)} F(s-n) \\ &= \sum_{k=0}^{n-1} \frac{\Gamma(1-s+k)}{\Gamma(1-s)} [f^{(n-k-1)}(t) t^{s-k-1}]_0^\infty \\ &\quad + \frac{\Gamma(1-s+n)}{\Gamma(1-s)} F(s-n) \end{aligned}$$

If $f(t)$ and $Re(s)$ turns all substitutions into zero, then

$$\mathcal{M}\{f^{(n)}(t); s\} = \frac{\Gamma(1-s+n)}{\Gamma(1-s)} F(s-n).$$

Mellin transform — basic facts

$f(t)$ is piece-wise continuous in every closed interval $[a, b] \subset (0, \infty)$

$$F(s) = \mathcal{M}\{f(t); s\} = \int_0^\infty f(t) t^{s-1} dt, \quad \gamma_1 < Re(s) < \gamma_2.$$



Hjalmar Mellin was G. M. Mittag-Leffler's student at the university in Helsinki

Inverse Mellin transform:

$$f(t) = \frac{1}{2\pi i} \int_{\gamma-i\infty}^{\gamma+i\infty} F(s) t^{-s} ds, \quad \gamma_1 < \gamma < \gamma_2.$$

(under the Dirichlet conditions in every closed interval $[a, b] \subset (0, \infty)$:
 $f(t)$ must have a finite number of extrema,
 must have a finite number of discontinuities,
 must be absolutely integrable.)

Mellin transform of the R-L integral

$${}_0D_t^{-\alpha} f(t) = \frac{1}{\Gamma(\alpha)} \int_0^t (t-\tau)^{\alpha-1} f(\tau) d\tau = \frac{t^\alpha}{\Gamma(\alpha)} \int_0^1 (1-\xi)^{\alpha-1} f(t\xi) d\xi = \frac{t^\alpha}{\Gamma(\alpha)} \int_0^\infty f(t\xi) g(\xi) d\xi$$

where $g(t) = \begin{cases} (1-t)^{\alpha-1}, & (0 \leq t < 1) \\ 0, & (t \geq 1) \end{cases}$

The Mellin transform of $g(t)$ is the Beta function:

$$\mathcal{M}\{g(t); s\} = B(\alpha, s) = \frac{\Gamma(\alpha)\Gamma(s)}{\Gamma(\alpha+s)}$$

Mellin transform — basic facts

From the definition we have:

$$\mathcal{M}\{t^\alpha f(t); s\} = \mathcal{M}\{f(t); s+\alpha\} = F(s+\alpha).$$

Mellin convolution:

$$\begin{aligned} f(t) * g(t) &= \int_0^\infty f(t\tau)g(\tau) d\tau \\ \mathcal{M}\left\{\int_0^\infty f(t\tau)g(\tau) d\tau; s\right\} &= F(s)G(1-s) \end{aligned}$$

Combining the above formulas:

$$\mathcal{M}\left\{t^\lambda \int_0^\infty \tau^\mu f(t\tau)g(\tau) d\tau; s\right\} = F(s+\lambda)G(1-s-\lambda+\mu)$$

Mellin transform of the R-L integral

We already have:

$$\mathcal{M}\left\{t^\lambda \int_0^\infty \tau^\mu f(t\tau)g(\tau) d\tau; s\right\} = F(s+\lambda)G(1-s-\lambda+\mu)$$

$${}_0D_t^{-\alpha} f(t) = \frac{t^\alpha}{\Gamma(\alpha)} \int_0^\infty f(t\xi)g(\xi) d\xi$$

$$\mathcal{M}\{g(t); s\} = B(\alpha, s) = \frac{\Gamma(\alpha)\Gamma(s)}{\Gamma(\alpha+s)}$$

$$\mathcal{M}\left\{{}_0D_t^{-\alpha} f(t); s\right\} = \frac{1}{\Gamma(\alpha)} F(s+\alpha)B(\alpha, 1-s-\alpha)$$

$$\mathcal{M}\left\{{}_0D_t^{-\alpha} f(t); s\right\} = \frac{\Gamma(1-s-\alpha)}{\Gamma(1-s)} F(s+\alpha)$$

Compare with

$$\mathcal{M}\{f^{(n)}(t); s\} = \frac{\Gamma(1-s+n)}{\Gamma(1-s)} F(s-n)$$

Mellin transform of the R-L derivative

Let us take $0 \leq n-1 < \alpha < n$. Then we have: ${}_0D_t^\alpha f(t) = \frac{d^n}{dt^n} {}_0D_t^{-(n-\alpha)} f(t)$.

$$\begin{aligned} \mathcal{M}\{ {}_0D_t^\alpha f(t); s \} &= \mathcal{M}\left\{ \frac{d^n}{dt^n} {}_0D_t^{-(n-\alpha)} f(t); s \right\} = \mathcal{M}\{ g^{(n)}; s \} \\ &= \sum_{k=0}^{n-1} \frac{\Gamma(1-s+k)}{\Gamma(1-s)} \left[g^{(n-k-1)}(t) t^{s-k-1} \right]_0^\infty + \frac{\Gamma(1-s+n)}{\Gamma(1-s)} G(s-n) \\ &= \sum_{k=0}^{n-1} \frac{\Gamma(1-s+k)}{\Gamma(1-s)} \left[\frac{d^{n-k-1}}{dt^{n-k-1}} {}_0D_t^{-(n-\alpha)} f(t) t^{s-k-1} \right]_0^\infty + \frac{\Gamma(1-s+n)}{\Gamma(1-s)} \frac{\Gamma(1-(s-n)-(n-\alpha))}{\Gamma(1-(s-n))} F(s-n+(n-\alpha)) \end{aligned}$$

or, after simplifications:

$$\mathcal{M}\{ {}_0D_t^\alpha f(t); s \} = \sum_{k=0}^{n-1} \frac{\Gamma(1-s+k)}{\Gamma(1-s)} \left[{}_0D_t^{n-k-1} f(t) t^{s-k-1} \right]_0^\infty + \frac{\Gamma(1-s+\alpha)}{\Gamma(1-s)} F(s-\alpha)$$

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Mellin transform of sequential derivatives

Recall notation:

$$\begin{aligned} {}_aD_t^{\sigma_m} &\equiv {}_aD_t^{\sigma_m} {}_aD_t^{\sigma_{m-1}} \dots {}_aD_t^{\sigma_1}; \\ {}_aD_t^{\sigma_{m-1}} &\equiv {}_aD_t^{\sigma_{m-1}} {}_aD_t^{\sigma_{m-2}} \dots {}_aD_t^{\sigma_1}; \\ \sigma_m &= \sum_{j=1}^m \alpha_j, \quad 0 < \alpha_j \leq 1, \quad (j=1, 2, \dots, m) \end{aligned}$$

It can be shown that

$$\mathcal{M}\{ {}_0D_t^{\sigma_m} f(t); s \} = \sum_{k=1}^m \frac{\Gamma(1-s+\sigma_m-\sigma_k)}{\Gamma(1-s)} \left[{}_0D_t^{\sigma_m-1} f(t) t^{s-\sigma_m+\sigma_k-1} \right]_0^\infty + \frac{\Gamma(1-s+\sigma_m)}{\Gamma(1-s)} F(s-\sigma_m)$$

If $f(t)$ and $Re(s)$ turn all substitutions into zero, then

$$\mathcal{M}\{ {}_0D_t^{\sigma_m} f(t); s \} = \frac{\Gamma(1-s+\sigma_m)}{\Gamma(1-s)} F(s-\sigma_m)$$

For functions with suitable behavior the Mellin transforms for R-L, Caputo, and M-R derivatives coincide.

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Mellin transform of the R-L derivative

We have obtained:

$$\mathcal{M}\{ {}_0D_t^\alpha f(t); s \} = \sum_{k=0}^{n-1} \frac{\Gamma(1-s+k)}{\Gamma(1-s)} \left[{}_0D_t^{n-k-1} f(t) t^{s-k-1} \right]_0^\infty + \frac{\Gamma(1-s+\alpha)}{\Gamma(1-s)} F(s-\alpha)$$

If $0 < \alpha < 1$, then:

$$\mathcal{M}\{ {}_0D_t^\alpha f(t); s \} = \left[{}_0D_t^{n-1} f(t) t^{s-1} \right]_0^\infty + \frac{\Gamma(1-s+\alpha)}{\Gamma(1-s)} F(s-\alpha)$$

If $f(t)$ and $Re(s)$ turn all substitutions into zero, then

$$\mathcal{M}\{ {}_0D_t^\alpha f(t); s \} = \frac{\Gamma(1-s+\alpha)}{\Gamma(1-s)} F(s-\alpha)$$

similar to the MT of R-L integral

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Useful property of the Mellin transform

For functions with suitable behavior we have:

$$\mathcal{M}\{ t^\alpha D^\alpha f(t); s \} = \frac{\Gamma(1-s)}{\Gamma(1-s-\alpha)} F(s)$$

Then

$$\begin{aligned} \mathcal{M}\left\{ \sum_{k=0}^n a_k t^{\alpha+k} D^{\alpha+k} f(t); s \right\} &= F(s) \Gamma(1-s) \sum_{k=0}^n \frac{a_k}{\Gamma(1-s-\alpha-k)} \\ &= \frac{\Gamma(s) \Gamma(1-s)}{\Gamma(1-s-\alpha)} \sum_{k=0}^n (-1)^k a_k \prod_{j=0}^{k-1} (s+\alpha+1) \end{aligned}$$

In particular,

$$\mathcal{M}\{ t^{\alpha+1} D^{\alpha+1} f(t) + t^\alpha D^\alpha f(t); s \} = \frac{\Gamma(1-s)(1-s-\alpha)}{\Gamma(1-s-\alpha)} F(s).$$

and for $\alpha = 1$ we have the well known property of the Mellin transform:

$$\mathcal{M}\{ t^2 f''(t) + t f'(t); s \} = s^2 F(s)$$

often used in applications

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Mellin transform of the Caputo derivative

Take $0 \leq n-1 < \alpha < n$ and denote $h(t) = f^{(n)}(t)$. Then:

$$\begin{aligned} \mathcal{M}\{ {}_0^C D_t^\alpha f(t); s \} &= \mathcal{M}\{ {}_0D_t^{-(n-\alpha)} f^{(n)}(t); s \} = \mathcal{M}\{ {}_0D_t^{-(n-\alpha)} h(t); s \} = \frac{1-s-(n-\alpha)}{\Gamma(1-s)} H(s+(n-\alpha)) \\ &= \sum_{k=0}^{n-1} \frac{\Gamma(1-s-n+\alpha+k)}{\Gamma(1-s)} \left[f^{(n-k-1)}(t) t^{s+n-\alpha-k-1} \right]_0^\infty + \frac{\Gamma(1-s+\alpha)}{\Gamma(1-s)} F(s-\alpha) \end{aligned}$$

If $0 < \alpha < 1$, then:

$$\mathcal{M}\{ {}_0^C D_t^\alpha f(t); s \} = \frac{\Gamma(\alpha-s)}{\Gamma(1-s)} \left[f(t) t^{s-\alpha} \right]_0^\infty + \frac{\Gamma(1-s+\alpha)}{\Gamma(1-s)} F(s-\alpha)$$

If $f(t)$ and $Re(s)$ turn all substitutions into zero, then

$$\mathcal{M}\{ {}_0^C D_t^\alpha f(t); s \} = \frac{\Gamma(1-s+\alpha)}{\Gamma(1-s)} F(s-\alpha)$$

similar to the MT of R-L integral and derivative

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Fractional Differential Equations

Existence and uniqueness of solutions



M. Escher, Balcony (1945)
R. Lichtenstein, Girl in Window (???)



A magician

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Existence and uniqueness of solutions

The simplest equation

Constructing a solution:

The Laplace transform of the sequential FD gives

$$s^{\sigma_n} Y(s) - \sum_{k=0}^{n-1} s^{\sigma_n - \sigma_{n-k}} [{}_0 D_t^{\sigma_{n-k-1}} y(t)]_{t=0} = F(s)$$

$$Y(s) = s^{-\sigma_n} F(s) + \sum_{k=0}^{n-1} b_{n-k} s^{-\sigma_{n-k}}$$

Inverse Laplace transform gives

$$y(t) = \frac{1}{\Gamma(\sigma_n)} \int_0^t (t-\tau)^{\sigma_n-1} f(\tau) d\tau + \sum_{k=0}^{n-1} \frac{b_{n-k}}{\Gamma(\sigma_{n-k})} t^{\sigma_{n-k}-1}$$

$$= \frac{1}{\Gamma(\sigma_n)} \int_0^t (t-\tau)^{\sigma_n-1} f(\tau) d\tau + \sum_{i=1}^n \frac{b_i}{\Gamma(\sigma_i)} t^{\sigma_i-1}$$

$i = n - k$

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Existence and uniqueness of solutions

Linear fractional differential equations

We shall consider the following IVP:

$${}_0 D_t^{\sigma_n} y(t) + \sum_{j=1}^{n-1} p_j(t) {}_0 D_t^{\sigma_{n-j}} y(t) + p_n(t) y(t) = f(t), \quad (0 < t < T < \infty)$$

$$[{}_0 D_t^{\sigma_k-1} y(t)]_{t=0} = b_k, \quad k = 1, \dots, n$$

where ${}_a D_t^{\sigma_k} \equiv {}_a D_t^{\sigma_k} {}_a D_t^{\sigma_{k-1}} \dots {}_a D_t^{\sigma_1}$; and $f(t) \in L_1(0, T)$, i.e.

$${}_a D_t^{\sigma_k-1} \equiv {}_a D_t^{\sigma_k-1} {}_a D_t^{\sigma_{k-1}} \dots {}_a D_t^{\sigma_1};$$

$$\sigma_k = \sum_{j=1}^k \alpha_j, \quad (k = 1, 2, \dots, n);$$

$$0 < \alpha_j \leq 1, \quad (j = 1, 2, \dots, n),$$

$$\int_0^T |f(t)| dt < \infty.$$

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Existence and uniqueness of solutions

The simplest equation

Checking if it is a solution:

Using the R-L derivative of the power function

and taking into account that $\frac{1}{\Gamma(-m)} = 0, \quad m = 0, 1, 2, \dots$,

we obtain

$${}_0 D_t^{\sigma_i} \left(\frac{t^{\sigma_i-1}}{\Gamma(\sigma_i)} \right) = \begin{cases} \frac{t^{\sigma_i-\sigma_k-1}}{\Gamma(\sigma_i-\sigma_k)}, & (k < i) \\ 0, & (k \geq i) \end{cases}$$

$${}_0 D_t^{\sigma_k-1} \left(\frac{t^{\sigma_i-1}}{\Gamma(\sigma_i)} \right) = \begin{cases} \frac{t^{\sigma_i-\sigma_k}}{\Gamma(1+\sigma_i-\sigma_k)}, & (k < i) \\ 1, & (k = i) \\ 0, & (k > i) \end{cases}$$

Direct substitution of $y(t)$ into the equation and the initial conditions shows that they are satisfied. A solution exists!

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Existence and uniqueness of solutions

The simplest equation

THEOREM I. If $f(t) \in L_1(0, T)$, then the equation

$${}_0 D_t^{\sigma_n} y(t) = f(t)$$

has the unique solution $y(t) \in L_1(0, T)$, which satisfies the initial conditions

$$[{}_0 D_t^{\sigma_k-1} y(t)]_{t=0} = b_k, \quad k = 1, \dots, n$$

PROOF. Let us construct the solution and then prove its uniqueness.

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Existence and uniqueness of solutions

The simplest equation

Proof of uniqueness:

Suppose there are two different solutions,

$$y_1(t), \quad y_2(t)$$

Then the function $z(t) = y_1(t) - y_2(t)$ satisfies

$${}_0 D_t^{\sigma_n} z(t) = 0,$$

$$[{}_0 D_t^{\sigma_k-1} z(t)]_{t=0} = 0, \quad k = 1, 2, \dots, n$$

But then the Laplace transform of $z(t)$ is $Z(s) = 0$, and $z(t) = 0$ almost everywhere in $(0, T)$.

Therefore, solution in $L_1(0, T)$ is unique. ■

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Existence and uniqueness of solutions

General linear fractional differential equations

THEOREM 2. If $f(t) \in L_1(0, T)$, and $p_j(t)$, ($j = 1, \dots, n$), are continuous functions in the closed interval $[0, T]$, then the initial-value problem

$${}_0\mathcal{D}_t^{\sigma_n} y(t) + \sum_{j=1}^{n-1} p_j(t) {}_0\mathcal{D}_t^{\sigma_{n-j}} y(t) + p_n(t) y(t) = f(t), \quad (0 < t < T < \infty)$$

$$[{}_0\mathcal{D}_t^{\sigma_{k-1}} y(t)]_{t=0} = b_k, \quad k = 1, \dots, n$$

has unique solution $y(t) \in L_1(0, T)$

PROOF. Let us use Theorem I for reducing the IVP to an integral equation of the Volterra type.

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Existence and uniqueness of solutions

General linear fractional differential equations

Since the coefficients $p_j(t)$ are continuous in $[0, T]$, the kernel can be written as a weakly singular kernel

$$K(t, \tau) = \frac{K^*(t, \tau)}{(t - \tau)^{1-\mu}},$$

where $K^*(t, \tau)$ is continuous for $0 \leq t \leq T$, $0 \leq \tau \leq T$, and

$$\mu = \min\{\sigma_n, \sigma_n - \sigma_{n-1}, \sigma_n - \sigma_{n-2}, \dots, \sigma_n - \sigma_1\} = \min\{\sigma_n, \alpha_n\}$$

Similarly, $g(t) = \frac{g^*(t)}{t^{1-\nu}}$, $g^*(t)$ is continuous in $[0, T]$

$$\nu = \min\{\sigma_1, \dots, \sigma_n; \alpha_2, \dots, \alpha_n\} = \min\{\alpha_1, \alpha_2, \dots, \alpha_n\}.$$

Obviously, $0 < \mu \leq 1$, $0 < \nu \leq 1$.

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Existence and uniqueness of solutions

General linear fractional differential equations

Let us introduce an auxiliary function by denoting

$${}_0\mathcal{D}_t^{\sigma_n} y(t) = \varphi(t).$$

Using Theorem I we can write

$$y(t) = \frac{1}{\Gamma(\sigma_n)} \int_0^t (t - \tau)^{\sigma_n - 1} \varphi(\tau) dt + \sum_{i=1}^n b_i \frac{t^{\sigma_i - 1}}{\Gamma(\sigma_i)}.$$

Substituting into the equation

$${}_0\mathcal{D}_t^{\sigma_n} y(t) + \sum_{k=1}^{n-1} p_{n-k}(t) {}_0\mathcal{D}_t^{\sigma_k} y(t) + p_n(t) y(t) = f(t).$$

we obtain... (see next slide)

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Existence and uniqueness of solutions

General linear fractional differential equations

It is known that the Volterra integral equation of the second kind with weakly singular kernel and with the right-hand side from $L_1(0, T)$ has a unique solution $\varphi(t) \in L_1(0, T)$. Then, according to Theorem I, the unique solution of the problem

$${}_0\mathcal{D}_t^{\sigma_n} y(t) = \varphi(t), \quad [{}_0\mathcal{D}_t^{\sigma_{k-1}} y(t)]_{t=0} = b_k, \quad k = 1, \dots, n$$

can be determined using the formula

$$y(t) = \frac{1}{\Gamma(\sigma_n)} \int_0^t (t - \tau)^{\sigma_n - 1} \varphi(\tau) dt + \sum_{i=1}^n b_i \frac{t^{\sigma_i - 1}}{\Gamma(\sigma_i)}. \quad \blacksquare$$

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Existence and uniqueness of solutions

General linear fractional differential equations

... (continued from the previous slide) we obtain:

$$\varphi(t) + \int_0^t K(t, \tau) \varphi(\tau) dt = g(t),$$

where

$$K(t, \tau) = p_n(t) \frac{(t - \tau)^{\sigma_n - 1}}{\Gamma(\sigma_n)} + \sum_{k=1}^{n-1} p_{n-k}(t) \frac{(t - \tau)^{\sigma_n - \sigma_k - 1}}{\Gamma(\sigma_n - \sigma_k)},$$

$$g(t) = f(t) - p_n(t) \sum_{i=1}^n b_i \frac{t^{\sigma_i - 1}}{\Gamma(\sigma_i)} - \sum_{k=1}^{n-1} p_{n-k}(t) \sum_{i=k+1}^n b_i \frac{t^{\sigma_i - \sigma_k - 1}}{\Gamma(\sigma_i - \sigma_k)}.$$

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Existence and uniqueness of solutions

Particular case: zero initial conditions

Why?

- zero initial conditions mean the absolute beginning of the process represented by the function
- there are difficulties with numerical approximation of initial conditions of the type
- the coincidence of the Riemann-Liouville, Grunwald-Letnikov, Caputo, and Miller-Ross derivatives in the case of a proper number of zero initial conditions on the function $y(t)$ and its integer-order derivatives; this coincidence withdraws misinterpretation of the problem formulation and solution

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Existence and uniqueness of solutions

Particular case: zero initial conditions

Suppose $m - 1 \leq \sigma_n < m$, $y^{(j)}(0) = 0$, $(j = 0, 1, \dots, m - 1)$.
Then we can replace sequential derivatives with R-L derivatives.

THEOREM 3. If $f(t)$ and $p_j(t)$, $(j = 1, \dots, n)$ are continuous functions in the closed interval $[0, T]$, then the initial-value problem

$${}_0D_t^{\sigma_n} y(t) + \sum_{j=1}^{n-1} p_j(t) {}_0D_t^{\sigma_{n-j}} y(t) + p_n(t) y(t) = f(t).$$

$$y^{(j)}(0) = 0, \quad (j = 0, 1, \dots, m - 1).$$

where $m - 1 \leq \sigma_n < m$, $\sigma_n > \sigma_{n-1} > \sigma_{n-2} > \dots > \sigma_2 > \sigma_1 > 0$,

has a unique solution $y(t)$, which is continuous in $[0, T]$

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Existence and uniqueness of solutions

General initial value problem (GIVP): outline of proof

STEP 1.

Reduce GIVP to an equivalent fractional integral equation: performing subsequently fractional integration of order $\alpha_n, \alpha_{n-1}, \dots, \alpha_1$ with the help of the composition rule

$${}_aD_t^{-p} ({}_aD_t^p f(t)) = f(t) - \sum_{j=1}^k [{}_aD_t^{p-j} f(t)]_{t=a} \frac{(t-a)^{p-j}}{\Gamma(p-j+1)}.$$

we obtain the equivalent integral equation:

$$y(t) = \sum_{i=1}^n \frac{b_i}{\Gamma(\sigma_i)} t^{\sigma_i-1} + \frac{1}{\Gamma(\sigma_n)} \int_0^t (t-\tau)^{\sigma_n-1} f(\tau, y(\tau)) d\tau.$$

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Existence and uniqueness of solutions

General initial value problem (GIVP)

GIVP:

$${}_0D_t^{\sigma_n} y(t) = f(t, y),$$

$$[{}_0D_t^{\sigma_k-1} y(t)]_{t=0} = b_k, \quad k = 1, \dots, n,$$

$$\begin{aligned} &{}_aD_t^{\sigma_k} \equiv {}_aD_t^{\sigma_n} {}_aD_t^{\sigma_{k-1}} \dots {}_aD_t^{\sigma_1}; \\ &{}_aD_t^{\sigma_{k-1}} \equiv {}_aD_t^{\sigma_{k-1}} {}_aD_t^{\sigma_{k-2}} \dots {}_aD_t^{\sigma_1}; \\ &\sigma_k = \sum_{j=1}^k \alpha_j, \quad (k = 1, 2, \dots, n); \\ &0 < \alpha_j \leq 1, \quad (j = 1, 2, \dots, n). \end{aligned}$$

Let us suppose that $f(t, y)$ is defined in a domain G of a plane (t, y) , and define a region $R(h, K) \subset G$ as a set of points $(t, y) \in G$, which satisfy the following inequalities:

$$0 < t < h, \quad \left| t^{1-\sigma_1} y(t) - \sum_{i=1}^n b_i \frac{t^{\sigma_i-\sigma_1}}{\Gamma(\sigma_i)} \right| \leq K.$$

h and K are constant.

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Existence and uniqueness of solutions

General initial value problem (GIVP): outline of proof

STEP 2.

Define the sequence of functions $y_0(t), y_1(t), y_2(t), \dots$,

$$y_0(t) = \sum_{i=1}^n \frac{b_i}{\Gamma(\sigma_i)} t^{\sigma_i-1},$$

$$y_m(t) = \sum_{i=1}^n \frac{b_i}{\Gamma(\sigma_i)} t^{\sigma_i-1} + \frac{1}{\Gamma(\sigma_n)} \int_0^t (t-\tau)^{\sigma_n-1} f(\tau, y_{m-1}(\tau)) d\tau,$$

$$m = 1, 2, 3, \dots$$

STEP 3.

Show that the limit $\lim_{m \rightarrow \infty} y_m(t)$ exists and gives the required solution of the integral equation, which is equivalent to the considered GIVP. ■

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Existence and uniqueness of solutions

General initial value problem (GIVP)

THEOREM 3. Let $f(t, y)$ be a real-valued continuous function, defined in the domain G , satisfying in G the Lipschitz condition with respect to y , i.e.,

$$|f(t, y_1) - f(t, y_2)| \leq A|y_1 - y_2|,$$

such that

$$|f(t, y)| \leq M < \infty \quad \text{for all } (t, y) \in G.$$

Let also

$$K \geq \frac{Mh^{\sigma_n-\sigma_1+1}}{\Gamma(1+\sigma_n)}.$$

Then there exists in the region $R(h, K)$ a unique and continuous solution $y(t)$ of the problem GIVP.

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Existence and uniqueness theorem as a method of solution

Consider the following IVP:

$${}_0D_t^{\sigma_n} y(t) = \lambda y(t)$$

$$[{}_0D_t^{\sigma_k-1} y(t)]_{t=0} = b_k, \quad k = 1, \dots, n.$$

Here we have $f(t, y) = \lambda y$. Following the proof of TH-4,

$$y_0(t) = \sum_{i=1}^n b_i \frac{t^{\sigma_i-1}}{\Gamma(\sigma_i)}, \quad y_m(t) = y_0(t) + \frac{\lambda}{\Gamma(\sigma_n)} \int_0^t (t-\tau)^{\sigma_n-1} y_{m-1}(\tau) d\tau$$

$$= y_0(t) + \lambda {}_0D_t^{-\sigma_n} y_{m-1}(t),$$

$$m = 1, 2, 3, \dots$$

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Existence and uniqueness theorem as a method of solution

Using fractional differentiation of the power function:

$$\begin{aligned}
 y_1(t) &= y_0(t) + \lambda {}_0D_t^{-\sigma_n} \left\{ \sum_{i=1}^n b_i \frac{t^{\sigma_i-1}}{\Gamma(\sigma_i)} \right\} \\
 &= y_0(t) + \lambda \sum_{i=1}^n b_i \frac{t^{\sigma_n+\sigma_i-1}}{\Gamma(\sigma_n+\sigma_i)}, \\
 y_2(t) &= y_0(t) + \lambda {}_0D_t^{-\sigma_n} y_1(t) \\
 &= y_0(t) + \lambda {}_0D_t^{-\sigma_n} \left\{ y_0(t) + \lambda \sum_{i=1}^n b_i \frac{t^{\sigma_n+\sigma_i-1}}{\Gamma(\sigma_n+\sigma_i)} \right\} \\
 &= y_0(t) + \lambda \sum_{i=1}^n b_i \frac{t^{\sigma_n+\sigma_i-1}}{\Gamma(\sigma_n+\sigma_i)} + \lambda^2 \sum_{i=1}^n b_i \frac{t^{2\sigma_n+\sigma_i-1}}{\Gamma(2\sigma_n+\sigma_i)} \\
 &= \sum_{i=1}^n b_i \sum_{k=0}^2 \frac{\lambda^k t^{k\sigma_n+\sigma_i-1}}{\Gamma(k\sigma_n+\sigma_i)},
 \end{aligned}$$

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Dependence of a solution on initial conditions

It follows from Theorem 5 that for every ε between 0 and h small changes in initial conditions cause only small changes of the solution in the interval $[\varepsilon, h]$, which does not contain zero.

On the other hand, the solution may change significantly in the interval $[0, \varepsilon]$. Indeed, if the non-disturbed initial conditions are zero ($b_k = 0, k = 1, 2, \dots, n$), then the non-disturbed solution $y(t)$ is continuous in $[0, \varepsilon]$, and therefore bounded. However, the solution $\tilde{y}(t)$, corresponding to the disturbed initial conditions, may contain terms of the form $\delta_i t^{\sigma_i-1}/\Gamma(\sigma_i)$, which for $\sigma_i < 1$ make the disturbed solution unbounded at $t = 0$.

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Existence and uniqueness theorem as a method of solution

It can be shown by induction that

$$y_m(t) = \sum_{i=1}^n b_i \sum_{k=0}^m \frac{\lambda^k t^{k\sigma_n+\sigma_i-1}}{\Gamma(k\sigma_n+\sigma_i)}, \quad m = 1, 2, 3, \dots$$

Taking $m \rightarrow \infty$ we obtain the solution:

$$y(t) = \sum_{i=1}^n b_i \sum_{k=0}^{\infty} \frac{\lambda^k t^{k\sigma_n+\sigma_i-1}}{\Gamma(k\sigma_n+\sigma_i)} = \sum_{i=1}^n b_i t^{\sigma_i-1} E_{\sigma_n, \sigma_i}(\lambda t^{\sigma_n})$$

If $n = 1$ and $\alpha_1 = 1$, then the considered problem becomes

$$y'(t) = \lambda y(t), \quad y(0) = b_1,$$

and the solution that we obtained becomes the classical one:

$$y(t) = b_1 E_{1,1}(\lambda t) = e^{\lambda t}.$$

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Dependence of a solution on initial conditions

Introduce small changes (disturbances) in initial conditions:

$$[{}_0D_t^{\sigma_k-1} y(t)]_{t=0} = b_k + \delta_k, \quad k = 1, \dots, n.$$

THEOREM 5. *Let the assumptions of the Theorem 4 hold.*

If $y(t)$ is a solution of GIVP, and $\tilde{y}(t)$ is a solution of the same equation satisfying the initial conditions with disturbances δ_k , then for $0 < t \leq h$ the following holds:

$$|y(t) - \tilde{y}(t)| \leq \sum_{i=1}^n |\delta_i| t^{\sigma_i-1} E_{\sigma_n, \sigma_i}(A t^{\sigma_n})$$

(h is the same as in Theorem 4.)

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