

$$D = \sqrt[3]{D_{12} \cdot D_{23} \cdot D_{13}}$$

$$L_1 = 2 \cdot 10^{-4} \cdot \ln \frac{\sqrt[3]{D_{12} \cdot D_{23} \cdot D_{13}}}{r_{zv} \cdot \sqrt[n]{\xi}}$$

$$L_1 = \frac{1,11 \cdot 10^{-2} \cdot \varepsilon_r}{C_1} + 0,05$$

$$L_1 = 0,46 \cdot \log \frac{R}{r} + 0,05$$

$$Z_1 = \frac{R_1}{n} + j \cdot \omega \cdot L_1$$

$$h_1 = H_1 - \frac{2}{3} \cdot f_{\max}; h = \sqrt[3]{h_1 \cdot h_2 \cdot h_3}$$

$$p = 18 \cdot 10^6 \cdot \ln \frac{2 \cdot h}{r_{zv}}$$

$$p_{vz} = 18 \cdot 10^6 \cdot \ln \frac{D'}{D}$$

$$p_{vz} = 18 \cdot 10^6 \cdot \ln \frac{\sqrt{4 \cdot h^2 + D^2}}{D}$$

$$p_{z1,z1} = 18 \cdot 10^6 \cdot \ln \frac{2 \cdot h_{z1}}{r_{z1}}$$

$$p_{v,z1} = 18 \cdot 10^6 \cdot \ln \sqrt[3]{\frac{D_{1z1'} \cdot D_{2z1'} \cdot D_{3z1'}}{D_{1z1} \cdot D_{2z1} \cdot D_{3z1}}}$$

$$p_s = \frac{ZL \cdot p_{v,z1}^2}{p_{z1,z1} + (ZL - 1) \cdot p_{z11,z12}}$$

$$C_1 = \frac{1}{(p - p_s) - (p_{vz} - p_s)}$$

$$C_0 = \frac{1}{(p - p_s) + 2 \cdot (p_{vz} - p_s)}$$

$$C_{vz} = C_1 \cdot C_0 \cdot (p_{vz} - p_s)$$

$$G_1 = \frac{\Delta P_{\text{priečne}}}{U_n^2}$$

$$Y_1 = G_1 + j \cdot \omega \cdot C_1$$

$$r_{zv} = \sqrt[n]{n \cdot r \cdot \rho^{(n-1)}}$$

$$\rho = \frac{a}{2 \cdot \sin \frac{\pi}{n}}$$

$$R = b + r + t_1 + t_2$$

$$\delta = \frac{1}{0,0242 \cdot \varepsilon_r} \cdot \log \frac{R^2 - b^2}{R \cdot r}$$

$$\delta' = \frac{1}{0,0242 \cdot \varepsilon_r} \cdot \log \sqrt{\frac{1 + \left(\frac{R}{b}\right)^2 + \left(\frac{b}{R}\right)^2}{3}}$$

$$C_1 = \frac{1}{\delta - \delta'}; C = \frac{1}{\delta + 2 \cdot \delta'}; C' = C_1 \cdot C \cdot \delta'$$

$$I_G = I_C \cdot \text{tg } \delta; I_C = \omega \cdot C_1 \cdot U_f$$

$$G = \frac{1}{R_i} = \frac{I_G}{U_f}$$

$$\Delta P_G = U_f \cdot I_G$$

$$C_1 = \frac{0,0242 \cdot \varepsilon_r}{\log \frac{R}{r}}$$

$$\gamma = \sqrt{Z_1 \cdot Y_1} = \beta + j \cdot \alpha$$

$$Z_0 = \sqrt{\frac{Z_1}{Y_1}}$$

$$S_p = \frac{U^2}{Z_0^*}$$

$$U_{1f} = U_{2f} \cdot \cosh(\gamma \cdot l) + I_2 \cdot Z_0 \cdot \sinh(\gamma \cdot l)$$

$$I_1 = I_2 \cdot \cosh(\gamma \cdot l) + \frac{U_{2f}}{Z_0} \cdot \sinh(\gamma \cdot l)$$

$$I_2 = \frac{S_2^*}{3 \cdot U_{2f}^*}$$

$$S_1 = 3 \cdot U_{1f} \cdot I_1^*; \Delta S_c = S_1 - S_2$$

$$\Delta U = U_{1f} - U_{2f}$$

$$\begin{bmatrix} U_{1f} \\ I_1 \end{bmatrix} = \begin{bmatrix} A & B \\ C & D \end{bmatrix} \cdot \begin{bmatrix} U_{2f} \\ I_2 \end{bmatrix}$$

II:

$$A = D = 1 + \frac{Z \cdot Y}{2}; B = Z; C = Y \cdot \left(1 + \frac{Z \cdot Y}{4}\right)$$

T:

$$A = D = 1 + \frac{Z \cdot Y}{2}; B = Z \cdot \left(1 + \frac{Z \cdot Y}{4}\right); C = Y$$

Γ:

$$A = 1; B = Z; C = Y; D = 1 + Z \cdot Y$$

$$\Delta S_{\text{pozdĺzne}} = \frac{3 \cdot \Delta U^2}{Z^*}$$

$$\Delta S_{\text{priečne}} = \frac{1}{2} \cdot Y^* \cdot (3 \cdot U_{f1}^2 + 3 \cdot U_{f2}^2)$$

$$Q_c = \text{Im}(\Delta S_{\text{priečne}})$$

$$\begin{aligned} \sinh(\gamma \cdot l) &= \sinh(\beta \cdot l + j \cdot \alpha \cdot l) = \\ &= \sinh(\beta \cdot l) \cdot \cos(\alpha \cdot l) + j \cdot \cosh(\beta \cdot l) \cdot \sin(\alpha \cdot l) \end{aligned}$$

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$$\varphi_1 = \langle U_1 \rangle - \langle I_1 \rangle$$

$$P_1 = 3 \cdot U_{1f} \cdot I_1 \cdot \cos \varphi_1$$

$$\Delta p_{\%} = \frac{P_1 - P_2}{P_1} \cdot 100$$